# Graphs with nonnegative resistance curvature

Karel Devriendt – University of Oxford (karel.devriendt@maths.ox.ac.uk)

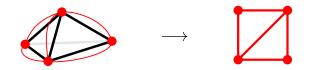
November 2024 - Graphternoon in Ghent

- 1. Graphs from simplices
- 2. Graph-theoretic characterization
- 3. Three results
- 4. Three questions

1. Graphs from simplices



1. Graphs from simplices



1. Graphs from simplices

$$\longrightarrow \quad \square$$

The acute skeleton of a simplex S is the graph G(S) with

$$V = \{ \text{vertices of S} \}$$
  

$$E = \{ uv : \text{ angle between } S \setminus u \text{ and } S \setminus v \text{ is acute } (< 90^{\circ}) \}$$



A simplex  $S \mbox{ is } \ldots$ 



A simplex S is ...  $\triangleright$  **non-obtuse** if all angles are non-obtuse ( $\leq 90^{\circ}$ )



A simplex S is ...  $\triangleright$  non-obtuse if all angles are non-obtuse ( $\leq 90^{\circ}$ )  $\triangleright$  centered if it is non-obtuse and S contains its circumcenter



A simplex S is ...  $\triangleright$  non-obtuse if all angles are non-obtuse ( $\leq 90^{\circ}$ )  $\triangleright$  centered if it is non-obtuse and S contains its circumcenter  $\triangleright$  well-centered if it is centered and S<sup>o</sup> contains its circumcenter



A simplex S is ...

- $\triangleright$  **non-obtuse** if all angles are non-obtuse ( $\leq 90^{\circ}$ )
- $\triangleright$  centered if it is non-obtuse and S contains its circumcenter
- $\triangleright$  well-centered if it is centered and  $S^\circ$  contains its circumcenter

Which graphs arise in this way?



A simplex S is ...

- $\triangleright$  **non-obtuse** if all angles are non-obtuse ( $\leq 90^{\circ}$ )
- $\triangleright$  centered if it is non-obtuse and S contains its circumcenter
- $\triangleright$  well-centered if it is centered and  $S^{\circ}$  contains its circumcenter

Which graphs arise in this way?

#### Theorem (Fiedler 2011)

The skeleton of a well-centered simplex S is 1-tough:



A simplex S is ...

- $\triangleright$  **non-obtuse** if all angles are non-obtuse ( $\leq 90^{\circ}$ )
- $\triangleright$  centered if it is non-obtuse and S contains its circumcenter
- $\triangleright$  well-centered if it is centered and  $S^{\circ}$  contains its circumcenter

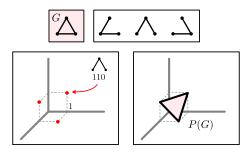
Which graphs arise in this way?

#### Theorem (Fiedler 2011)

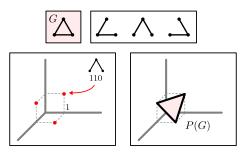
The skeleton of a well-centered simplex S is 1-tough: to disconnect G(S) in  $k \ge 2$  components, at least k vertices must be removed from G(S).

- 2. Graph-theoretic characterization
- ▶ The ingredients (1)

- 2. Graph-theoretic characterization
- ▶ The ingredients (1)



- 2. Graph-theoretic characterization
- ▶ The ingredients (1)

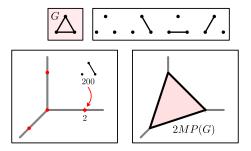


A spanning tree of G is a maximal acyclic subgraph  $T \subseteq G$ .

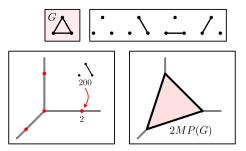
**Spanning tree polytope** P(G) is the convex hull of  $\chi_{E(T)}$  over all STs.

- 2. Graph-theoretic characterization
- ► The ingredients (2)

- 2. Graph-theoretic characterization
- ► The ingredients (2)



- 2. Graph-theoretic characterization
- ► The ingredients (2)



A matching of G is a subgraph  $M \subseteq G$  with maximum degree 1.

**2-matching polytope** is the convex hull of  $2\chi_{E(M)}$  over all matchings.

# 2. Graph-theoretic characterization

# 2. Graph-theoretic characterization

Theorem (D. 2024+)

The following are equivalent for a connected graph G:

# 2. Graph-theoretic characterization

# Theorem (D. 2024+)

The following are equivalent for a connected graph G:

1. G is the skeleton of some centered simplex;

2. Graph-theoretic characterization

The following are equivalent for a connected graph G:

- 1. G is the skeleton of some centered simplex;
- 2. G admits a positive distribution on its spanning trees, such that every vertex has expected degree  $\leq 2$  under this distribution;

2. Graph-theoretic characterization

The following are equivalent for a connected graph G:

- 1. G is the skeleton of some centered simplex;
- 2. G admits a positive distribution on its spanning trees, such that every vertex has expected degree  $\leq 2$  under this distribution;
- 3.  $P(G)^{\circ} \cap 2MP(G)$  is nonempty.

2. Graph-theoretic characterization

The following are equivalent for a connected graph G:

- 1. G is the skeleton of some centered simplex;
- 2. G admits a positive distribution on its spanning trees, such that every vertex has expected degree  $\leq 2$  under this distribution;
- 3.  $P(G)^{\circ} \cap 2MP(G)$  is nonempty.

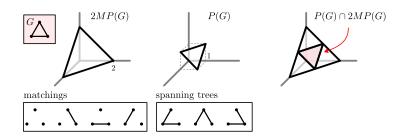
We call these graphs resistance nonnegative (RN).

2. Graph-theoretic characterization

The following are equivalent for a connected graph G:

- 1. G is the skeleton of some centered simplex;
- 2. G admits a positive distribution on its spanning trees, such that every vertex has expected degree  $\leq 2$  under this distribution;
- 3.  $P(G)^{\circ} \cap 2MP(G)$  is nonempty.

We call these graphs resistance nonnegative (RN).



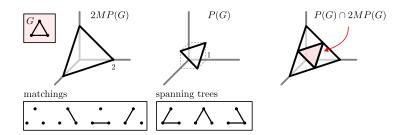
2. Graph-theoretic characterization

The following are equivalent for a connected graph G:

- 1. *G* is the skeleton of some well-centered simplex;
- 2. G admits a positive distribution on its spanning trees, such that every vertex has expected degree < 2 under this distribution;

3. 
$$P(G)^{\circ} \cap 2MP(G)^{\circ}$$
 is nonempty.

We call these graphs resistance positive (RP).



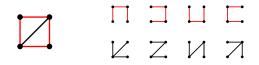
Corollary

Hamiltonian graphs are RP but the converse does not hold (e.g. Petersen).

# Corollary

Hamiltonian graphs are RP but the converse does not hold (e.g. Petersen).

Proof idea:



 $(1-\varepsilon)$  × uniform distribution on Hamiltonian paths  $\varepsilon$  × uniform distribution on all other trees

#### Corollary

Hamiltonian graphs are RP but the converse does not hold (e.g. Petersen).

#### Corollary

Deciding if G is RN is a linear program.

#### Corollary

Hamiltonian graphs are RP but the converse does not hold (e.g. Petersen).

#### Corollary

Deciding if G is RN is a linear program.

#### Corollary

If G is RN and even/odd, then G has a perfect/near perfect matching.

**Question:** Does there exist finite  $t \ge 1$  such that *t*-tough implies RP ?

**Question:** Does there exist finite  $t \ge 1$  such that *t*-tough implies RP ?

 $\triangleright$  We know: Hamiltonian  $\subsetneq$  RP  $\subseteq$  1-tough

**Question:** Does there exist finite  $t \ge 1$  such that *t*-tough implies RP ?

 $\triangleright$  We know: Hamiltonian  $\subsetneq$  RP  $\subseteq$  1-tough

 $\triangleright$  Chvátal's conjecture:  $\exists t>2$  such that t-tough implies Hamiltonian

**Question:** Does there exist finite  $t \ge 1$  such that *t*-tough implies RP ?

 $\triangleright$  We know: Hamiltonian  $\subsetneq$  RP  $\subseteq$  1-tough

 $\triangleright$  Chvátal's conjecture:  $\exists t > 2$  such that t-tough implies Hamiltonian

**Question:** What is computational complexity of " $G \in RN$ "?

**Question:** Does there exist finite  $t \ge 1$  such that *t*-tough implies RP ?

 $\triangleright$  We know: Hamiltonian  $\subsetneq$  RP  $\subseteq$  1-tough

 $\triangleright$  Chvátal's conjecture:  $\exists t > 2$  such that t-tough implies Hamiltonian

**Question:** What is computational complexity of " $G \in RN$ " ?

 $\triangleright$  Exponentially-sized (in |E|) linear program

**Question:** Does there exist finite  $t \ge 1$  such that *t*-tough implies RP ?

 $\triangleright$  We know: Hamiltonian  $\subsetneq$  RP  $\subseteq$  1-tough

 $\triangleright$  Chvátal's conjecture:  $\exists t>2$  such that t-tough implies Hamiltonian

**Question:** What is computational complexity of " $G \in RN$ " ?

 $\triangleright$  Exponentially-sized (in |E|) linear program  $\triangleright P(G)$  is matroid polytope

**Question:** Does there exist finite  $t \ge 1$  such that *t*-tough implies RP ?

 $\triangleright$  We know: Hamiltonian  $\subsetneq$  RP  $\subseteq$  1-tough

 $\triangleright$  Chvátal's conjecture:  $\exists t > 2$  such that t-tough implies Hamiltonian

**Question:** What is computational complexity of " $G \in RN$ " ?

 $\triangleright$  Exponentially-sized (in |E|) linear program  $\triangleright P(G)$  is matroid polytope

Question: Which planar graphs are RN ?

**Question:** Does there exist finite  $t \ge 1$  such that *t*-tough implies RP ?

▷ We know: Hamiltonian  $\subsetneq$  RP  $\subseteq$  1-tough

 $\triangleright$  Chvátal's conjecture:  $\exists t > 2$  such that t-tough implies Hamiltonian

**Question:** What is computational complexity of " $G \in RN$ " ?

 $\triangleright$  Exponentially-sized (in |E|) linear program  $\triangleright$  P(G) is matroid polytope

Question: Which planar graphs are RN ?

 $\triangleright$  RN = "nonnegative scalar curvature"

**Question:** Does there exist finite  $t \ge 1$  such that *t*-tough implies RP ?

 $\triangleright$  We know: Hamiltonian  $\subsetneq$  RP  $\subseteq$  1-tough

 $\triangleright$  Chvátal's conjecture:  $\exists t > 2$  such that t-tough implies Hamiltonian

**Question:** What is computational complexity of " $G \in RN$ " ?

 $\triangleright$  Exponentially-sized (in |E|) linear program  $\triangleright P(G)$  is matroid polytope

Question: Which planar graphs are RN ?

 $\triangleright$  RN = "nonnegative scalar curvature"

Other suggestions or comments are welcome!

# Thank you! Questions?

karel.devriendt@maths.ox.ac.uk

"Graphs with nonnegative resistance curvature" Karel Devriendt, arXiv:2410.07756 [math.CO]