

# On minimum leaf spanning trees and a criticality notion

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**Abstract.** The minimum leaf number of a connected non-hamiltonian graph  $G$  is the number of leaves of a spanning tree of  $G$  with the fewest leaves among all spanning trees of  $G$ . Based on this quantity, Wiener introduced leaf-stable and leaf-critical graphs, concepts which generalise hypotractability and hypohamiltonicity. In this article, we present new methods to construct leaf-stable and leaf-critical graphs and study their properties. Furthermore, we improve several bounds related to these families of graphs. These extend previous results of Horton, Thomassen, and Wiener.

**Key Words.** Spanning tree, minimum leaf number, leaf-stable, leaf-critical

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## 1 Introduction

Let  $G$  be a graph and  $\mathcal{T}(G)$  the set of all spanning trees of  $G$ . Denote by  $\ell(T)$  the number of leaves of a tree  $T$ . The *minimum leaf number*  $\text{ml}(G)$  of  $G$  is defined as

$$\text{ml}(G) = \begin{cases} \infty & \text{if } G \text{ is not connected,} \\ \min_{T \in \mathcal{T}(G)} \ell(T) & \text{if } G \text{ is connected but not hamiltonian,} \\ 1 & \text{if } G \text{ is hamiltonian.} \end{cases}$$

Wiener [13] introduced the following. Consider an integer  $\ell \geq 2$ . A connected graph  $G$  with  $\text{ml}(G) = \ell$  is called  *$\ell$ -leaf-critical* if  $\text{ml}(G - v) = \ell - 1$  for every

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$v \in V(G)$ , and  $\ell$ -leaf-stable if  $\text{ml}(G - v) = \ell$  for every  $v \in V(G)$ . A graph is *hypohamiltonian* (*hypotraceable*) if it is non-hamiltonian (non-traceable), yet all of its vertex-deleted subgraphs are hamiltonian (traceable)—for an overview we refer to Holton and Sheehan’s survey [4], and for recent results, see [6]. The family of all 2-leaf-critical graphs (3-leaf-critical graphs) and the family of all hypohamiltonian (hypotraceable) graphs coincide.

Wiener showed that  $\ell$ -leaf-stable and  $\ell$ -leaf-critical graphs exist for every  $\ell \geq 2$ . He also studied these graphs under the additional condition of planarity. Among the applications of these results is the affirmative answer to the question of Gargano et al. [1, p. 93] whether non-traceable non-hypotraceable arachnoid graphs (defined in [1]) exist, see [13].

Determining the minimum leaf number  $\text{ml}(G)$  plays an important role in designing efficient networks, but this minimisation problem is obviously NP-hard, since  $\text{ml}(G) = 1$  if and only if  $G$  is hamiltonian and  $\text{ml}(G) = 2$  if and only if  $G$  is traceable. Actually, Lu and Ravi [7] showed that the problem does not even have a constant factor approximation, unless  $P = NP$ . On the other hand, approximation algorithms to maximise the number of non-leaves of spanning trees exist, see e.g. [9].

In [13], Wiener asked for constructions of  $\ell$ -leaf-critical graphs of connectivity 2 for  $\ell \geq 4$ , and for determining (or at least bounding the order of) the smallest  $\ell$ -leaf-critical graphs. Note that there exist 3-leaf-critical graphs of connectivity 2, see [10]. Applying a result of Thomassen [11], we answer the first request in Section 2 (see Theorem 1). This is summarised in Proposition 2 in Section 4.

We also give new constructions of  $\ell$ -leaf-stable graphs, which will be discussed in Section 3 (see Theorems 4 and 5). This improves the known bounds on smallest  $\ell$ -leaf-stable graphs with a specified connectivity, which are further discussed in Proposition 3 in Section 4.

We will call a path starting at a vertex  $v$  a  $v$ -path, and a  $v$ -path ending at a vertex  $w \neq v$  a  $vw$ -path. For a graph  $G$  and a subgraph  $H$  of  $G$ ,  $d_H(v)$  denotes the degree of  $v$  in  $H$ . If  $S$  is a set, we write  $|S|$  for its cardinality. Consider a graph  $G$  of connectivity  $k$  which is not a complete graph. Then  $G$  contains a  $k$ -vertex-cut  $A$ . Denote with  $C_1, \dots, C_p$  the connected components of  $G - A$ , where  $p \geq 2$ . We say that  $F_i = G[V(C_i) \cup A]$  is a  $k$ -fragment of  $G$ , and that  $A$  is the set of *vertices of attachment* of  $F_i$ . When we simply speak of a  $k$ -fragment, we refer to a graph which can be obtained as the  $k$ -fragment of some graph of connectivity  $k$ . A  $k$ -fragment is *trivial* if it has exactly  $k + 1$  vertices.

## 2 Construction of $k$ -leaf-critical graphs

We now present a method to construct  $k$ -leaf-critical graphs using fragments of 3-leaf-critical graphs for any  $k \geq 3$ . For the proof of the next theorem we need a result of Thomassen which we now recall:

**Lemma 1** (Thomassen [11]). *Let  $i \in \{1, 2\}$  and  $G = F_1 \cup F_2$  be a graph with  $V(F_1) \cap V(F_2) = \{x, y\}$  and  $F_i - V(F_{3-i}) \neq \emptyset$ . Suppose that  $G$  is hypotraceable. Then  $F_i$  has no hamiltonian path starting at  $x$  or  $y$ , and if  $z \in V(F_i)$ , then  $F_i - z$  has a hamiltonian path starting at  $x$  or  $y$ . Conversely, if these properties are satisfied, then  $G$  is hypotraceable.*

**Theorem 1.** *Let  $k \geq 2$  and  $F_i$  be pairwise disjoint 2-fragments of 3-leaf-critical graphs with vertices of attachment  $\{x_i, y_i\}$  for  $0 \leq i \leq k-1$ , respectively. Identifying  $y_i$  with  $x_{i+1}$ , indices taken mod  $k$ , we obtain a  $(k+1)$ -leaf-critical graph  $G$ .*

*Proof.* We first recall certain facts concerning 2-fragments of 3-leaf-critical (i.e. hypotraceable) graphs—their proofs follow from Thomassen’s characterisation of such fragments, see Lemma 1. It is easy to see that 3-leaf-critical graphs have minimum degree at least 3, thus these fragments must be non-trivial. Let  $F$  be a 2-fragment of a 3-leaf-critical graph with vertices of attachment  $x$  and  $y$ . Then the following hold.

- (a)  $F$  does not contain a hamiltonian  $x$ -path or  $y$ -path.
- (b) There exists a hamiltonian  $x$ -path or  $y$ -path in  $F - v$  for every  $v \in V(F)$ . In particular:
- (c)  $F - x$  and  $F - y$  contain a hamiltonian  $y$ -path and  $x$ -path, respectively.
- (d)  $F$  has a spanning tree with exactly three leaves, namely  $x, y, v$ , where  $v \in V(F) \setminus \{x, y\}$ .

Let  $i \in \{0, \dots, k-1\}$  be fixed and arbitrary. Indices are to be taken mod  $k$  and we shall treat  $F_i$  as a subgraph of  $G$ . Let  $z_i$  be the vertex in  $G$  obtained when identifying  $y_i$  with  $x_{i+1}$ , and let  $T$  be a spanning tree of  $G$ .

**Claim 1.** *For every  $i = 0, 1, \dots, k-1$ ,  $F_i$  contains a leaf of  $T$  different from  $z_i$  and  $z_{i-1}$ .*

*Proof of Claim 1.* Let  $T_i$  be the subgraph of  $T$  spanned by the vertex set of  $F_i$  and  $c_i$  the number of components of  $T_i$ . It is obvious that  $T_i$  is a forest containing  $c_i$  trees and that vertices of  $T_i$  different from  $z_i$  and  $z_{i-1}$  have the same degree in  $T$  and  $T_i$ . Now we distinguish two cases.

Case 1.  $c_i \geq 2$ . If there is no isolated vertex in  $T_i$ , then  $\ell(T_i) \geq 4$ . Since vertices of  $T_i$  different from  $z_i$  and  $z_{i-1}$  have the same degree in  $T$  and  $T_i$ , there must be at least two leaves of  $T$  in  $F_i - \{z_i, z_{i-1}\}$ . If  $T_i$  contains an isolated vertex, then it can only be  $z_i$  or  $z_{i-1}$ , but not both, therefore a component different from the isolated vertex contains a leaf of  $T$  different from  $z_i$  and  $z_{i-1}$ .

Case 2.  $c_i = 1$ . Now  $T_i$  is a tree. If it is a path, then  $z_i$  and  $z_{i-1}$  cannot be the end-vertices of the path because of fact (a), thus the end-vertices are leaves of  $T$  different from  $z_i$  and  $z_{i-1}$ . If  $T_i$  is not a path then it has at least three leaves, one of which must be a leaf of  $T$  different from  $z_i$  and  $z_{i-1}$ . ■

It follows directly from the above claim that  $\ell(T) \geq k$ . Let us now prove that  $\ell(T) \geq k+1$ . If  $\ell(T) = k$ , then each  $F_i$  contains just one leaf of  $T$  different from  $z_i$  and  $z_{i-1}$  and by the proof of Claim 1 it follows that each  $T_i$  is either a tree with three leaves such that both  $z_i$  and  $z_{i-1}$  are leaves, or  $T_i$  contains an isolated vertex which is either  $z_i$  or  $z_{i-1}$ . It is obvious that the latter situation must occur for exactly one  $i$ : if it would not occur at all, then  $T$  would contain a cycle and if it would occur for at least two  $i$ ’s, then  $T$  would not be connected. Now if  $T_j$  is the

subgraph that contains the isolated vertex, which is (say)  $z_j$ , then  $z_j$  is also a leaf of  $T$ , thus  $\ell(T) \geq k + 1$ , a contradiction from which  $\text{ml}(G) \geq k + 1$  immediately follows. A spanning tree of  $G$  with exactly  $k + 1$  leaves is easy to describe: use fact (d) in  $F_0, \dots, F_{k-2}$  and fact (c) in  $F_{k-1}$ .

We now prove that  $\text{ml}(G - v) = k$  for every  $v \in V(G)$ . If  $v = z_i$  for some  $i$ , then let us use fact (d) for  $F_j$  with  $j \notin \{i, i + 1\}$  and fact (c) for  $F_i$  and  $F_{i+1}$ . Gluing together the trees and paths guaranteed by the facts we obtain a spanning tree of  $G - z_i$  with  $k$  leaves.

Consider now  $v \in V(F_i) \setminus \{z_{i-1}, z_i\}$ . By fact (b), there exists a hamiltonian  $z_i$ -path or a hamiltonian  $z_{i-1}$ -path in  $F_i - v$  (suppose w.l.o.g. that it is a  $z_{i-1}$ -path). Now let us use fact (d) for  $F_j$  with  $j \notin \{i, i + 1\}$  and fact (c) for  $F_{i+1}$  (there is a hamiltonian  $z_{i+1}$ -path in  $F_{i+1} - z_i$ ). Once more we join the trees and paths guaranteed by the facts and obtain a spanning tree of  $G - v$  with  $k$  leaves, proving that  $\text{ml}(G - v) \leq k$  for every  $v \in V(G)$ . Since  $\text{ml}(G) = k + 1$ , it is easy to see that  $\text{ml}(G - v) \geq \text{ml}(G) - 1 = k$ . Therefore,  $\text{ml}(G - v) = k$  for every  $v \in V(G)$  finishing the proof of the  $(k + 1)$ -leaf-criticality of  $G$ .  $\square$

For Theorem 1 to be useful, we need 2-fragments of 3-leaf-critical graphs—fortunately, Thomassen [10] showed that 3-leaf-critical graphs of connectivity 2 exist. Theorem 1 thus provides  $\ell$ -leaf-critical graphs of connectivity 2 for any  $\ell \geq 3$ . We shall summarise in Section 4 bounds obtainable through Theorem 1.

We have seen that 2-fragments of 3-leaf-critical graphs can be used to obtain  $k$ -leaf-critical graphs for any  $k \geq 3$ . We end this section with a brief discussion of 2-fragments of leaf-critical graphs (here and in the remainder of this section, we suppress the prefix “ $k$ -” in  $k$ -leaf-critical, as the exact value of  $k$  shall play no role in the arguments) motivated by Thomassen’s characterisation of 2-fragments of hypotraceable graphs [11].

**Theorem 2.** *Every 1-fragment of a 2-fragment of a leaf-critical graph is also a 2-fragment of a leaf-critical graph.*

For the proof of this theorem we need the following immediate corollary of [13, Lemmas 4.4 and 4.6] characterising 2-fragments of leaf-critical graphs.

**Theorem 3.** *Let  $F_1$  and  $F_2$  be disjoint 2-fragments of leaf-critical (possibly different) graphs with vertices of attachment  $x, y$  and  $w, z$ , respectively, and let  $G$  be the graph obtained from the union of  $F_1$  and  $F_2$  by identifying  $x$  with  $w$  and  $y$  with  $z$ . Then  $G$  is a leaf-critical graph.*

*Proof of Theorem 2.* Let  $F$  be a 2-fragment of a leaf-critical graph with vertices of attachment  $x, y$  and a cut-vertex  $z$ . Let  $F'$  be a copy of  $F$  and  $x', y', z'$  the copies of  $x, y, z$ , respectively. Let now  $G$  be the graph obtained from the union of  $F$  and  $F'$  by identifying  $x$  with  $x'$  and  $y$  with  $y'$  and let us denote the vertices obtained by  $x''$  and  $y''$ , respectively. Then  $G$  is a leaf-critical graph by Theorem 3. Since leaf-critical graphs are 2-connected,  $F - z$  has just two components, one of which contains  $x$  and the other one contains  $y$ . It is obvious that  $\{x'', z\}$  and  $\{y'', z\}$  are vertex-cuts of  $G$  showing that indeed the 1-fragments of  $F$  are 2-fragments of a leaf-critical graph, namely  $G$ .  $\square$

We end this section by mentioning a result of Wiener [13], who proved that gluing together a 2-fragment of an  $\ell$ -leaf-critical graph and a 2-fragment of a  $k$ -leaf-critical graph, we obtain an  $(\ell + k - 3)$ -leaf-critical graph. (Note that non-3-connected  $j$ -leaf-critical graphs exist only if  $j \geq 3$ .)

### 3 Construction of $k$ -leaf-stable graphs

#### 3.1 Connectivity 2

Wiener showed in [13, Theorem 7.1] that if  $G$  is a 3-leaf-critical graph with a 2-vertex-cut  $\{x, y\}$ , then  $xy \notin E(G)$  and  $G + xy$  is 2-leaf-stable. We now present a  $k$ -leaf-stable analogue of this result, but with an edge-connectivity requirement imposed on all 2-fragments. For its proof we need a definition and the following lemma. A graph  $G$  is called *almost hypohamiltonian* if  $G$  is non-hamiltonian and  $G$  contains a vertex  $w$  such that  $G - w$  is non-hamiltonian, yet  $G - v$  is hamiltonian for every  $v \in V(G) \setminus \{w\}$ .

**Lemma 2.** *Let  $F$  be a 2-fragment of a 3-leaf-critical graph with vertices of attachment  $x$  and  $y$ , and let  $v \in V(F)$ . If  $F$  contains a non-trivial 2-edge-cut then there exists no hamiltonian  $xy$ -path in  $F - v$ .*

*Proof.* Due to Theorem 3.1 of [14] we know that by deleting the edges of a non-trivial 2-edge-cut of a 2-fragment  $F$  of a hypotraceable (that is, 3-leaf-critical) graph, we obtain two components  $F_1$  and  $F_2$  that are both either vertex-deleted hypohamiltonian or almost hypohamiltonian graphs. Moreover, in the proof of the theorem the following are also shown:

1. The vertices  $x$  and  $y$  are in different components  $F_i$  (let us suppose w.l.o.g. that  $x \in V(F_1)$ ,  $y \in V(F_2)$ ).
2. If the edges of the 2-edge-cut are  $a_1a_2$  and  $b_1b_2$  such that  $a_i, b_i \in V(F_i)$  for  $i = 1, 2$ , then the vertices  $a_1, a_2, b_1, b_2$  are pairwise different and there is no hamiltonian path in  $F_1$  whose end-vertices lie in  $\{x, a_1, b_1\}$  and there is no hamiltonian path in  $F_2$  whose end-vertices lie in  $\{y, a_2, b_2\}$ .

Now let us suppose to the contrary that there exists a hamiltonian  $xy$ -path  $P$  in  $F - v$ , where we may assume that  $v \in V(F_1) \setminus \{x\}$ . Then  $P \cap F_2$  must be a hamiltonian path between  $y$  and one of  $a_2$  and  $b_2$ , a contradiction.  $\square$

**Theorem 4.** *Let  $G$  be a graph obtained as in Theorem 1 and  $z_i$  be the vertex in  $G$  obtained when identifying  $y_i$  with  $x_{i+1}$ . If each  $F_i$  has edge-connectivity 2, then  $G + z_i z_j$  is  $k$ -leaf-stable for any  $i, j$  with  $i \neq j$ .*

*Proof.* All terminology is as given in the statement and proof of Theorem 1. Let  $i, j \in \{0, \dots, k-1\}$  be arbitrary but fixed with  $i \neq j$ . By Theorem 1,  $G$  is  $(k+1)$ -leaf-critical, so  $\text{ml}(G) = k+1$  and  $\text{ml}(G - v) = k$  for all  $v \in V(G)$ . Put  $G' = G + z_i z_j$ . In the following we consider  $G$  to be a subgraph of  $G'$ .

On one hand, as in  $G$ , in  $G'$  every  $F_i$  must contain a leaf of a spanning tree of  $G'$ , so  $\text{ml}(G') \geq k$  (this can be seen in the same fashion as in the proof of Theorem 1).

On the other hand, it is easy to construct a spanning tree of  $G'$  with exactly  $k$  leaves: this tree contains the edge  $z_i z_j$  and uses fact (c) in  $F_i$  and  $F_j$ , and fact (d) in all other 2-fragments. Thus  $\text{ml}(G') = k$ .

Consider  $v \in V(G')$ . Clearly,  $v \in V(F_t)$  for some  $t$ . Since  $F_t$  has edge-connectivity 2, by Lemma 2 there is no hamiltonian  $z_t z_{t+1}$ -path in  $F_t - v$ . So each  $F_i$  contains at least one leaf of any spanning tree of  $G' - v$ , in other words  $\text{ml}(G' - v) \geq k$ . Finally,  $\text{ml}(G - v) = k$  implies that  $\text{ml}(G' - v) \leq k$ , so  $\text{ml}(G' - v) = k$ .  $\square$

As we will see later in Proposition 3 in Section 4, there are 2-fragments of 3-leaf-critical graphs with edge-connectivity 2. Thus we can construct  $k$ -leaf-stable graphs by Theorem 4.

It is worth mentioning that when we “glue”—i.e. identify the cut-vertices using a bijection—two leaf-critical fragments we obtain a leaf-critical graph, see [13, Lemma 4.6]. However, this is not true for leaf-stable graphs.

Motivated by Thomassen’s 1978 question whether hypohamiltonian graphs with minimum degree at least 4 exist [12], minimum degrees have played an important role in various classes of non-hamiltonian graphs with rich hamiltonian properties. An example of such a result is [15, Theorem 4.3(ii)]: For every  $d \geq 2$  there exists a non-hamiltonian graph  $G$  with minimum degree  $d$  in which every vertex-deleted subgraph is traceable. In other words,  $\text{ml}(G) \geq 2$  and  $\text{ml}(G - v) \leq 2$  for all  $v \in V(G)$ . This can be achieved by considering the cartesian product of a triangle and  $P_2$ , and replacing each of the three copies of  $P_2$  by  $P_4$  when  $d = 2$  and  $K_{d+1}$  if  $d > 2$  (where the end-vertices of the copy of  $P_2$  are replaced by the end-vertices of the copy of  $P_4$ , or two arbitrary vertices in the complete graph). Note that all of these graphs have connectivity 2. We leave to the reader the straightforward verification that, in fact, these graphs are 2-leaf-stable, i.e.  $\text{ml}(G) = \text{ml}(G - v) = 2$  for all  $v \in V(G)$ . Thus, there exist for every  $d \geq 2$  graphs that are 2-leaf-stable and have minimum degree  $d$ . We propose the following relaxation of Thomassen’s question mentioned above: Do 3-connected leaf-stable or leaf-critical graphs with minimum degree at least 4 exist?

### 3.2 Connectivity 3

In this section, we construct for each  $k \geq 3$  infinitely many  $k$ -leaf-stable graphs which, for appropriate input graphs, have connectivity 3. In order to proceed, we need some terminology. Let  $H$  be a graph with a cubic vertex  $x$  satisfying the following three conditions:

- (H1)  $H$  is non-hamiltonian.
- (H2) For every  $v \in N(x)$  the graph  $H - v$  is hamiltonian.
- (H3) For any edge  $e$  incident with  $x$  there is a hamiltonian  $x$ -path in  $H$  using  $e$ .

We say that such a graph  $H$  is *good* and call the vertex  $x$  *special*. For example, consider the Petersen graph with any vertex acting as a special vertex.

Consider a cubic graph  $G$  and let  $H$  be a graph containing a cubic vertex  $x$ . We denote by  $G \cdot H_x$  the graph obtained when the following operation is performed for every vertex  $v \in V(G)$ : we remove  $v$ , take a copy  $H^v$  of  $H$  (disjoint from  $G$ ) and

the copy  $x^v$  of  $x$  in each  $H^v$ , and join in  $G - v$  and  $H^v - x^v$ , using a bijection, each vertex in  $N_G(v)$  with each vertex in  $N_{H^v}(x^v)$  by an edge. By the construction, we can regard the edge set  $E(G)$  as a subset of the edge set of  $G \cdot H_x$ ; an edge  $uv$  in  $G$  corresponds to the edge connecting a vertex in  $N_{H^u}(x^u)$  and a vertex in  $N_{H^v}(x^v)$ . We illustrate this operation in Fig. 1.

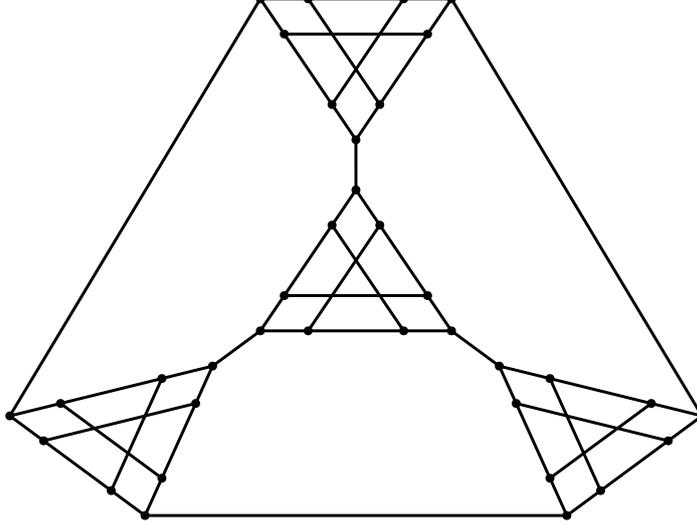


Fig. 1:  $K_4 \cdot P_x$ , where  $P$  is the Petersen graph and  $x$  is an arbitrary vertex of  $P$ . This particular example was already studied in the seventies [17].

For a tree  $T$  and for a positive integer  $i$ , let  $V_i(T)$  be the set of vertices of degree exactly  $i$  in  $T$ . Thus, we have  $\ell(T) = |V_1(T)|$ .

**Theorem 5.** *Let  $G$  be a 2-edge-connected cubic graph and  $H$  good with special vertex  $x$ . Then  $G \cdot H_x$  is  $(|V(G)|/2 + 1)$ -leaf-stable.*

*Proof.* First we show that  $\text{ml}(G \cdot H_x) \leq |V(G)|/2 + 1$ . Let  $T$  be a spanning tree of  $G$ . We consider the set  $\mathcal{P}$  of all non-trivial paths among the components of  $G - E(T)$  (and ignore isolated vertices and cycles). Since  $T$  is a spanning tree of the cubic graph  $G$ , we have  $|V(G)| = \ell(T) + |V_2(T)| + |V_3(T)|$  and  $\ell(T) = |V_3(T)| + 2$ , which implies  $|V(G)| = 2\ell(T) + |V_2(T)| - 2$ . Since any end-vertex of  $P \in \mathcal{P}$  belongs to  $V_2(T)$  and any vertex in  $V_2(T)$  is an end-vertex of some path  $P \in \mathcal{P}$ , we also have  $|V_2(T)| = 2|\mathcal{P}|$ . These imply

$$\ell(T) + |\mathcal{P}| = \frac{|V(G)| - |V_2(T)| + 2}{2} + \frac{|V_2(T)|}{2} = \frac{|V(G)|}{2} + 1. \quad (1)$$

Consider  $v \in V(G)$ . We denote by  $H^v$  the copy of  $H$  replacing the vertex  $v$  and, abusing notation, by  $x^v$  the copy of  $x$  in  $H^v$ . Put  $N_{H^v}(x^v) = \{x_1^v, x_2^v, x_3^v\}$ . The following claim follows from the fact that  $H$  is good.

**Claim 2.** *All of the following hold.*

(C1)  $H^v - x^v$  contains a spanning tree whose leaves are exactly  $x_1^v, x_2^v, x_3^v$ .

(C2) For every  $i \in \{1, 2, 3\}$ ,  $H^v - x^v$  contains a hamiltonian  $x_i^v$ -path.

(C3) For every pairwise distinct  $i, j, k \in \{1, 2, 3\}$ ,  $H^v - x^v$  contains a spanning forest with exactly two components, one of which is an  $x_i^v x_j^v$ -path and the other one is an  $x_k^v$ -path.

*Proof of Claim 2.* If  $V(H^v) = \{x^v, x_1^v, x_2^v, x_3^v\}$ , then condition (H2) immediately shows that  $H^v$  is isomorphic to  $K_4$ , contradicting condition (H1).

Thus, there exists a vertex  $y$  in  $H^v - \{x^v, x_1^v, x_2^v, x_3^v\}$  with an edge  $x_i^v y$  for some  $i \in \{1, 2, 3\}$ , say  $i = 1$ . By condition (H2),  $H^v - x^v - x_1^v$  contains a hamiltonian  $x_2^v x_3^v$ -path and then adding  $x_1^v$  with the edge  $x_1^v y$  gives a spanning tree desired in (C1). Condition (H3) with specifying the edge  $x^v x_i^v$  as  $e$  and deleting  $x^v$  give a hamiltonian  $x_i^v$ -path in  $H^v - x^v$ . Hence (C2) is satisfied. (C3) is a direct corollary of (C1).  $\blacksquare$

In  $T$ , we will distinguish the following four types of vertices  $v$  in  $G$ : (i)  $d_T(v) = 3$ , (ii)  $d_T(v) = 2$ , (iii)  $d_T(v) = 1$  and  $v \notin V(P)$  for all  $P \in \mathcal{P}$  (in this case  $v$  belongs to a cycle in  $G - E(T)$ ), (iv)  $d_T(v) = 1$  and there exists a  $P \in \mathcal{P}$  such that  $d_P(v) = 2$ .

We now define a spanning forest  $\mathfrak{T}^v$  of  $H^v - x^v$  for each vertex  $v$ . First consider a vertex  $v$  of type (i), (iii) and (iv).

(i)  $d_T(v) = 3$ . Due to (C1),  $H^v - x^v$  contains a spanning tree  $\mathfrak{T}^v$  whose leaves are exactly  $x_1^v, x_2^v, x_3^v$ .

(iii)  $d_T(v) = 1$  and  $v \notin V(P)$  for all  $P \in \mathcal{P}$ . Let  $i \in \{1, 2, 3\}$  such that  $x_i^v$  is an end-vertex of the edge corresponding to the edge in  $T$  incident to  $v$ . Due to (C2), there is a hamiltonian path  $\mathfrak{T}^v$  in  $H^v - x^v$  with end-vertex  $x_i^v$ .

(iv)  $d_T(v) = 1$  and there exists a  $P \in \mathcal{P}$  such that  $d_P(v) = 2$ . Let  $k \in \{1, 2, 3\}$  such that  $x_k^v$  is an end-vertex of the edge corresponding to the edge in  $T$  incident to  $v$ , and let  $\{i, j\} = \{1, 2, 3\} - \{k\}$ . Due to (C3), there is a spanning forest  $\mathfrak{T}^v$  in  $H^v - x^v$  with exactly two components, one of which is an  $x_i^v x_j^v$ -path and the other one is an  $x_k^v$ -path.

Finally we deal with type (ii) vertices  $v$  of  $G$ . Note that for each  $P \in \mathcal{P}$ , there are two such vertices, each corresponding to an end-vertex of  $P$ . Let  $v(P)$  and  $w(P)$  be the end-vertices of  $P$ . For  $v(P)$ , let  $k \in \{1, 2, 3\}$  such that  $x_k^{v(P)}$  is an end-vertex of the edge corresponding to the one in  $P$  incident to  $v(P)$ , and let  $\{i, j\} = \{1, 2, 3\} - \{k\}$ . Due to (C3), there is a spanning forest  $\mathfrak{T}^{v(P)}$  in  $H^{v(P)} - x^{v(P)}$  with exactly two components, one of which is an  $x_i^{v(P)} x_j^{v(P)}$ -path and the other one is an  $x_k^{v(P)}$ -path. On the other hand, for  $w(P)$ , due to (C1),  $H^{w(P)} - x^{w(P)}$  contains a spanning tree  $\mathfrak{T}^{w(P)}$  whose leaves are exactly  $x_1^{w(P)}, x_2^{w(P)}, x_3^{w(P)}$ .

Let  $\mathfrak{T}$  be the subgraph of  $G \cdot H_x$  obtained from  $T \cup \bigcup_{P \in \mathcal{P}} P$  by replacing each vertex  $v$  with  $\mathfrak{T}^v$ . By the construction, it is not difficult to see that  $\mathfrak{T}$  contains all vertices in  $G \cdot H_x$  and no cycle. Now we count the number of edges in  $\mathfrak{T}$ . For each  $v \in V(G)$ , we have

$$|E(\mathfrak{T}^v)| = \begin{cases} |V(H)| - 2 & \text{if } v \text{ is of either type (i), or type (iii),} \\ & \text{or type (ii) and } v = w(P) \text{ for some } P \in \mathcal{P}, \\ |V(H)| - 3 & \text{if } v \text{ is of either type (ii) and } v = v(P) \text{ for some } P \in \mathcal{P}, \\ & \text{or type (iv).} \end{cases}$$

There are exactly  $|\mathcal{P}|$  vertices  $v$  of type (ii) with  $v = v(P)$  for some  $P \in \mathcal{P}$ . Note that all inner vertices in  $P \in \mathcal{P}$  are of type (iv), and hence there are exactly

$\sum_{P \in \mathcal{P}} (|V(P)| - 2)$  vertices of type (iv). Thus, we obtain

$$\begin{aligned}
|E(\mathfrak{T})| &= |E(T)| + \sum_{P \in \mathcal{P}} |E(P)| + \sum_{v \in V(G)} |E(\mathfrak{T}^v)| \\
&= |V(G)| - 1 + \sum_{P \in \mathcal{P}} (|V(P)| - 1) + |V(G)| (|V(H)| - 2) \\
&\qquad\qquad\qquad - |\mathcal{P}| - \sum_{P \in \mathcal{P}} (|V(P)| - 2) \\
&= |V(G)| (|V(H)| - 1) - 1 = |V(G \cdot H_x)| - 1.
\end{aligned}$$

Since  $\mathfrak{T}$  contains no cycle, it must be a spanning tree of  $G \cdot H_x$ .

Furthermore, any leaf of  $\mathfrak{T}$  is either an end-vertex in  $\mathfrak{T}^v$  other than  $x_i^v$  for some vertex  $v$  of type (iii), or the vertex  $x_k^v$  for some vertex  $v$  of type (iv), or the vertex  $x_k^{v(P)}$  for some  $P \in \mathcal{P}$ . Therefore, it follows from equality (1) that

$$\ell(\mathfrak{T}) = \ell(T) + |\mathcal{P}| = \frac{|V(G)|}{2} + 1.$$

Therefore, we have  $\text{ml}(G \cdot H_x) \leq |V(G)|/2 + 1$ .

Next we prove  $\text{ml}(G \cdot H_x) \geq |V(G)|/2 + 1$ . Let  $\mathfrak{T}$  be a spanning tree of  $G \cdot H_x$ . A vertex  $v$  in  $G$  is said to be *full* if  $\mathfrak{T} \cap (H^v - x^v)$  is connected and  $|E_G(v) \cap E(\mathfrak{T})| = 3$ , where  $E_G(v)$  is the set of edges incident with  $v$  in  $G$ . Otherwise  $v$  is *non-full*. The following claim plays a crucial role in the proof.

**Claim 3.** *For any non-full vertex  $v$ , the copy  $H^v - x^v$  corresponding to  $v$  contains at least one leaf of  $\mathfrak{T}$ .*

*Proof of Claim 3.* If  $\mathfrak{T} \cap (H^v - x^v)$  is disconnected or  $|E_G(v) \cap E(\mathfrak{T})| = 1$ , then clearly  $H^v - x^v$  contains at least one leaf of  $\mathfrak{T}$ . Suppose that  $\mathfrak{T} \cap (H^v - x^v)$  is connected and  $|E_G(v) \cap E(\mathfrak{T})| = 2$ . In this case, if  $H^v - x^v$  does not contain a leaf of  $\mathfrak{T}$ , then  $\mathfrak{T} \cap (H^v - x^v)$  is a hamiltonian path in  $H^v - x^v$  connecting two vertices in  $\{x_1^v, x_2^v, x_3^v\}$ . However, adding  $x^v$  to  $\mathfrak{T} \cap (H^v - x^v)$  through two edges incident with  $x^v$ , we obtain a hamiltonian cycle of a copy of  $H$ , contradicting condition (H1). Thus,  $\mathfrak{T} \cap (H^v - x^v)$  contains a leaf of  $\mathfrak{T}$ .  $\blacksquare$

Now, we show that  $\mathfrak{T}$  contains at least  $|V(G)|/2 + 1$  leaves. By Claim 3, if there are at least  $|V(G)|/2 + 1$  non-full vertices in  $G$ , then we are done. Thus, we may assume that there are at most  $|V(G)|/2$  non-full vertices in  $G$ , which implies that there are at least  $|V(G)|/2$  full vertices in  $G$ . Since for each full vertex  $v$  in  $G$ , the graph  $H^v - x^v$  contains a vertex of degree at least three in  $\mathfrak{T}$ , we see that  $|V_3(\mathfrak{T})| \geq |V(G)|/2$ . Therefore, we have

$$\ell(\mathfrak{T}) = |V_3(\mathfrak{T})| + 2 \geq |V(G)|/2 + 2,$$

and we are also done.

Finally, we prove that  $\text{ml}(G \cdot H_x - w) = |V(G)|/2 + 1$  for any vertex  $w$  in  $G \cdot H_x$ . Let  $w$  be a vertex in  $G \cdot H_x$ , and let  $u$  be the vertex in  $G$  such that  $w$  is a vertex in  $H^u - x^u$ .

Since  $G$  is 2-edge-connected and cubic,  $G$  contains a spanning tree  $T_u$  such that  $u$  is a leaf of  $T_u$ . (For example, take a depth-first-search from  $u$ .) Then by the same argument as we have shown  $\text{ml}(G \cdot H_x) \leq |V(G)|/2 + 1$ , starting from the spanning tree  $T_u$ , we can find a spanning tree of  $G \cdot H_x$  with at most  $|V(G)|/2 + 1$  leaves. Therefore, we have  $\text{ml}(G \cdot H_x - w) \leq |V(G)|/2 + 1$ . Thus, it suffices to show that  $\text{ml}(G \cdot H_x - w) \geq |V(G)|/2 + 1$ .

Let  $\mathfrak{T}'$  be a spanning tree of  $G \cdot H_x - w$ , and define a *full* vertex and a *non-full* vertex in  $G$  with respect to  $\mathfrak{T}'$ . In this case, we obtain the following claim. We omit its proof since it is the same as the proof of Claim 3.

**Claim 4.** *For any non-full vertex  $v$  such that  $v \neq u$ , the copy  $H^v - x^v$  corresponding to  $v$  contains at least one leaf of  $\mathfrak{T}'$ .*

Now we show that  $\mathfrak{T}'$  contains at least  $|V(G)|/2 + 1$  leaves. By Claim 4, if there are at least  $|V(G)|/2 + 2$  non-full vertices in  $G$ , then we are done. Therefore, we may assume that there are at most  $|V(G)|/2 + 1$  non-full vertices in  $G$ , which implies that there are at least  $|V(G)|/2 - 1$  full vertices in  $G$ . Since for each full vertex  $v$  in  $G$ , the graph  $H_x^v$  contains a vertex of degree at least three in  $\mathfrak{T}'$ , we see that  $|V_3(\mathfrak{T}')| \geq |V(G)|/2 - 1$ . Therefore, we have

$$\ell(\mathfrak{T}') = |V_3(\mathfrak{T}')| + 2 \geq |V(G)|/2 + 1,$$

and we are done. This completes the proof of Theorem 5.  $\square$

With the appropriate good graphs, Theorem 5 can be used to obtain  $\ell$ -leaf-stable graphs satisfying various additional properties. For example, since the Petersen graph is good, it gives a 3-edge-connected  $\ell$ -leaf-stable cubic graph of order  $18\ell - 18$  for  $\ell \geq 3$ . In fact, any hypohamiltonian graph satisfies conditions (H1)–(H3), so we can construct infinitely many 3-edge-connected  $\ell$ -leaf-stable cubic graphs. We also note here that multigraphs (i.e. graphs in which two vertices may be connected by more than one edge) may be used as good graphs.

Neyt [8] found the 24-vertex graph  $H'$  given in Fig. 2.  $H'$  is a non-hamiltonian graph in which all vertex-deleted subgraphs are traceable. Considering the vertex  $x$ , specified in Fig. 2, as its special vertex guarantees the goodness of  $H'$ ; we leave to the reader the straightforward verification of conditions (H2)–(H3).

As described above, we use Theorem 5 and Petersen's graph (as  $H$ ) to obtain a  $\ell$ -leaf-stable graph of order  $18(\ell - 1)$  for  $\ell \geq 3$ . We can also construct an  $\ell$ -leaf-stable planar graph of order  $46(\ell - 1)$  by Theorem 5 with  $H = H'$ , i.e. the 24-vertex graph depicted in Fig. 2. In either case any bridgeless cubic graph can be chosen as  $G$ .

**Corollary 1.** *For each  $\ell \geq 3$ , there are  $\ell$ -leaf-stable graphs of order  $18(\ell - 1)$  and  $\ell$ -leaf-stable planar graphs of order  $46(\ell - 1)$ .*

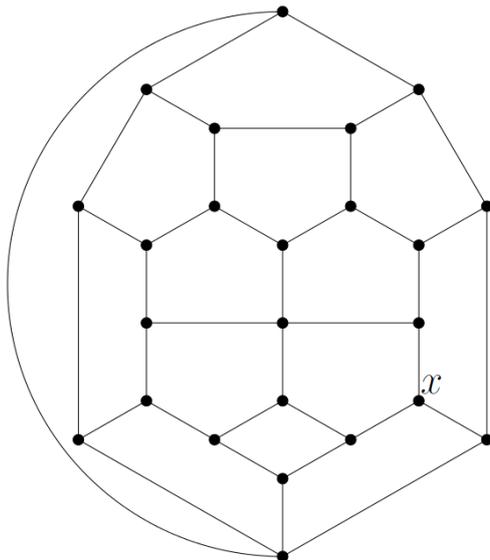


Fig. 2: A good polyhedral graph on 24 vertices due to Neyt [8].

Motivated by the usefulness of good graphs, we end this section with a structural result concerning good graphs and their toughness. In the following  $\omega(G)$  denotes the number of connected components of a possibly disconnected graph  $G$ .

**Proposition 1.** *Every good graph is 1-tough.*

*Proof.* Consider  $G$  to be a good graph,  $x$  its special vertex, and  $v$  a neighbour of  $x$ . Let us assume that  $G$  is not 1-tough, i.e. there exists an  $A \subseteq V(G)$  such that  $\omega(G - A) > |A|$ . By (H2),  $G - v$  is hamiltonian, so it is also 1-tough, therefore  $\omega(G - v - A) \leq |A|$ . As  $G - v - A$  is obviously the same as  $G - A - v$ , this means that  $G - A - v$  has fewer components than  $G - A$ . This is possible only if  $v$  is an isolated vertex of  $G - A$ , which implies that  $x \in A$ , since  $v$  and  $x$  are adjacent in  $G$ . Let now  $A' := A - x$ . Observe that as (H1) holds,  $G$  has a hamiltonian  $x$ -path, so  $G - x$  is traceable, which implies  $\omega(G - x - X) \leq |X| + 1$  for any  $X \subseteq V(G) \setminus \{x\}$ . Substituting  $X = A'$  we obtain

$$\omega(G - A) = \omega(G - x - A') \leq |A'| + 1 = |A|,$$

a contradiction. □

## 4 Small leaf-stable and leaf-critical graphs

As mentioned earlier, Wiener [13] expressed interest in determining the orders of the smallest  $\ell$ -leaf-stable and  $\ell$ -leaf-critical graphs. Let  $S_\kappa^\ell$  ( $R_\kappa^\ell$ ) be the order of the smallest  $\ell$ -leaf stable ( $\ell$ -leaf critical) graph of connectivity  $\kappa$ .  $\overline{S}_\kappa^\ell$  and  $\overline{R}_\kappa^\ell$  denote the respective numbers for the planar case. Whenever for certain  $\kappa$  and  $\ell$  no such numbers exist, we set them to be  $\infty$ . We here give a summary of the known bounds on the aforementioned numbers, including our new ones, but remark that nothing is known for  $\kappa \geq 4$ . In particular, Thomassen's question whether 4-connected hypohamiltonian graphs exist [12], i.e.  $R_{\geq 4}^2 = ?$ , remains open.

Thomassen [10] showed that  $R_2^3 \leq 34$ , Wiener [14] proved that  $\overline{R}_2^3 \leq 138$  and  $R_3^3 \leq 40$  is due to Horton [5]. We can generalise these as follows.

**Proposition 2.** *For  $\ell \geq 3$ , we have*

$$R_2^\ell \leq 17(\ell - 1), \quad \overline{R}_2^\ell \leq 69(\ell - 1), \quad R_3^2 = 10, \quad 23 \leq \overline{R}_3^2 \leq 40, \\ R_3^\ell \leq 16\ell - 8, \quad \text{and} \quad \overline{R}_3^\ell \leq 76\ell - 38.$$

*Proof.* Every 2-leaf-critical graph is 3-connected, so  $R_2^2 = \overline{R}_2^2 = \infty$ . The first two inequalities follow from Theorem 1 applied to Thomassen’s 18-vertex 2-fragment  $A$  of a 3-leaf-critical graph [10] and the 70-vertex planar analogue  $B$  (constructed from two copies of a planar 36-vertex almost hypohamiltonian graph with a cubic exceptional vertex, discovered independently by Wiener [14], and Goedgebeur and Zamfirescu [3]), respectively—no smaller such fragments are known.

$R_3^2 = 10$  is given by Petersen’s graph and the well-known fact that it is the smallest 2-leaf-critical graph.

The lower and upper bound for the order of the smallest planar 2-leaf-critical graph was established in [2] and [6], respectively.

The final two inequalities are based on Wiener’s [13, Theorem 3.8]. For the non-planar case we use the Petersen graph, while for the planar case we use the smallest known planar 2-leaf-critical graph [6], which has order 40.  $\square$

We also give a counterpart of Proposition 2 for the leaf-stable case.

**Proposition 3.** *For  $\ell \geq 3$ , we have*

$$S_2^2 = \overline{S}_2^2 = 12, \quad S_2^\ell \leq 17\ell, \quad \overline{S}_2^\ell \leq 69\ell, \\ S_3^\ell \leq \min\{18(\ell - 1), 16\ell\}, \quad \text{and} \quad \overline{S}_3^\ell \leq 46(\ell - 1).$$

*Proof.* The equalities follow from computational results of Van Cleemput and Zamfirescu [15]. Both  $S_2^2 \leq 12$  and  $\overline{S}_2^2 \leq 12$  are given by the same (planar) graph, obtained by adding in the cartesian product of  $K_3$  and  $P_2$  on each copy of  $P_2$  two extra vertices.

The first and the second inequality are obtained by applying Theorem 4 to the fragments  $A$  and  $B$ , defined in the proof of Proposition 2, respectively.

The  $16\ell$  bound of the third inequality is given in the article [13] of Wiener, while the remaining two bounds are given by Corollary 1.  $\square$

We end this paper with a problem motivated by work of Thomassen [12]: He proved that every planar 2-leaf-critical graph contains a cubic vertex. Zamfirescu [15] showed that there exist planar 2-leaf-stable graphs with no cubic vertices. Contrasting this, in [16] he proved—using a result of Wiener—that planar 3-leaf-critical graphs of connectivity 2 in which every 2-fragment has edge-connectivity 2 must contain a cubic vertex. However, the general case is open, and the same holds for planar 3-leaf-stable graphs.

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